

Cointegration

Basic Ideas and Key results

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September 14–19, 2009

Motivation

Economic theory often suggests that certain pairs of economic or financial variables should be linked by a **long-run** economic relationship.

Arbitrage arguments imply that the $I(1)$ prices of certain financial time series are linked.

The framework of cointegration deals with regression models with $I(1)$ data.

Idea Behind Cointegration

Many economic or financial time series appear to be $I(1)$:

- $I(1)$ variables tend to diverge as $T \rightarrow \infty$, because their unconditional variances are proportional to T .
- Thus, it may seem that $I(1)$ variables could never be expected to obey any sort of long-run equilibrium relationship.

It is possible for two (or more) variables to be $I(1)$, and yet a certain **linear combination** of those variables to be $I(0)$!

If that is the case, the $I(1)$ variables are said to be **cointegrated**:

- If two or more $I(1)$ variables are cointegrated, they must obey an equilibrium relationship in the long-run, although they may diverge substantially from that equilibrium in the short run.

Some Examples

- The permanent income hypothesis (PIH) implies cointegration between consumption and income.
- Money demand models imply cointegration between money, nominal income, prices, and interest rates.
- Growth theory models imply cointegration between income, consumption, and investment.
- Purchasing power parity (PPP) implies cointegration between the nominal exchange rate and foreign and domestic prices.
- The Fisher equation implies cointegration between nominal interest rates and inflation.
- The expectations hypothesis of the term structure implies cointegration between nominal interest rates at different maturities.

Cointegration

Consider two time series $y_{1,t}$ and $y_{2,t}$, known to be $I(1)$:

- Let y_1 and y_2 denote T -vectors:

$$\begin{matrix} y_1 \\ (T \times 1) \end{matrix} = \begin{bmatrix} y_{1,1} \\ y_{1,2} \\ \vdots \\ y_{1,T} \end{bmatrix} \qquad \begin{matrix} y_2 \\ (T \times 1) \end{matrix} = \begin{bmatrix} y_{2,1} \\ y_{2,2} \\ \vdots \\ y_{2,T} \end{bmatrix}$$

- $y_{1,t}$ and $y_{2,t}$ will be cointegrated if there exists a vector $\eta \equiv (1, \eta_2)'$ such that, when $y_{1,t}$ and $y_{2,t}$ are in **equilibrium**:

$$[y_1 \ y_2] \eta \equiv y_1 - \eta_2 y_2 = 0$$

- The η is called a **cointegrating vector**.
- It is clearly not unique!

Cointegration

Realistically, $y_{1,t}$ and $y_{2,t}$ are likely to be changing over time systematically as well as stochastically.

Cointegrating relationship:

$$Y\eta = X\beta$$

- $Y = [y_1 \ y_2]$
- $X =$ nonstochastic matrix (i.e., constant, trends)

Cointegration

Relationship $[y_1 \ y_2]\eta = 0$ cannot be expected to hold exactly for all t .

Equilibrium error:

$$\nu_t = y_t' \eta - x_t' \beta$$

In the general case when $Y = [y_1 \ y_2 \ \dots \ y_m]$, the m series $y_{1,t}, y_{2,t}, \dots, y_{m,t}$ are said to be **cointegrated** if there exists a vector η such that the equilibrium error ν_t is $I(0)$.

Common Trends

Consider the following two trend-stationary $I(1)$ series:

$$y_{1,t} = \alpha_1 + \beta_1 t + u_{1,t}$$

$$y_{2,t} = \alpha_2 + \beta_2 t + u_{2,t}$$

- $\{u_{1,t}\}_{t=-\infty}^{\infty}$ and $\{u_{2,t}\}_{t=-\infty}^{\infty}$ are white noise processes.

Linear combination of $y_{1,t}$ and $y_{2,t}$ with $\eta = (1, -\eta)'$:

$$\nu_t = (\alpha_1 - \eta\alpha_2) + (\beta_1 - \eta\beta_2)t + u_{1,t} - \eta u_{2,t}$$

- ν_t , in general, is still $I(1)$.
- The only way the ν_t series can be made $I(0)$ is if $\eta = \beta_1/\beta_2$.
- The effect of combining the two series is to remove the **common** linear trend.

Common Trends

Consider the following two independent random walk processes:

$$y_{1,t} = w_{1,t}$$

$$y_{2,t} = w_{2,t}$$

- $w_{i,t} = w_{i,t-1} + \epsilon_{i,t}$
- $\epsilon_{i,t}$, $i = 1, 2$, are two independent white noise processes.

Any linear combination of $y_{1,t}$ and $y_{2,t}$ must involve random walks $w_{1,t}$ and $w_{2,t}$:

- $y_{1,t}$ and $y_{2,t}$ cannot be cointegrated unless $w_{1,t} = w_{2,t}$
- Once again, $y_{1,t}$ and $y_{2,t}$ must have a **common** trend.

Common Trends

In a bivariate case, the end result is that if $y_{1,t}$ and $y_{2,t}$ are cointegrated, then they must share exactly one common stochastic or deterministic trend.

This observation, readily generalizes to multivariate cointegration:

- A set of m series that are cointegrated can be written as a covariance-stationary component plus a linear combination of a smaller set of common trends.
- The effect of cointegration is to purge these common trends from the resultant series.

Obvious econometric questions:

- How to estimate the cointegrating vector η ?
- How to test whether two or more variables are in fact cointegrated?

Estimating Cointegrating Vectors

Cointegrating relationship between m series $(y_{1,t}, y_{2,t}, \dots, y_{m,t})$ can, in general, be written as

$$\nu_t = y_t' \eta - x_t' \beta$$

Rewrite the above equation as a linear regression and use OLS to estimate η :

$$y_1 = X\beta + Y^* \eta^* + \nu$$

- Coefficient of y_1 is arbitrarily normalized to unity.
- $Y^* = [y_2 \ y_3 \ \dots \ y_m]$.
- Parameter vector η^* is equal to minus the $(m - 1)$ free elements of the parameter vector η .

Estimating Cointegrating Vectors

Two potentially serious problems:

- **Endogeneity**: If $(y_{1,t}, y_{2,t}, \dots, y_{m,t})$ are cointegrated, they are surely determined **jointly**. The error term ν_t will almost certainly be correlated with the regressors!
- **Spurious regression**: We are regressing an $I(1)$ variable on one or more other $I(1)$ variables!

Nevertheless, OLS may be used to obtain a consistent estimate of a normalized cointegrating vector η .

Properties of the OLS Estimator of η^*

Important caveats (see Stock (1987) and Phillips (1991)):

- $T(\hat{\eta}^* - \eta^*)$ converges in distribution to a nonnormal RV not necessarily centered at zero.
- The OLS estimator $\hat{\eta}^*$ is consistent and converges to η^* at rate T instead of the usual rate \sqrt{T} . That is, $\hat{\eta}^*$ is **super consistent**.
- Asymptotically, there is no simultaneity bias.
- In general, the asymptotic distribution of $T(\hat{\eta}^* - \eta^*)$ is asymptotically biased and nonnormal. The usual OLS standard errors are **not** correct.
- Even though the asymptotic bias goes to zero as $T \rightarrow \infty$, $\hat{\eta}^*$ may be substantially biased in finite samples.
- The OLS estimator $\hat{\eta}^*$ is also not efficient.

Dynamic OLS (DOLS)

Asymptotically more efficient estimates of η^* may be obtained by DOLS (see Stock & Watson 1993):

$$y_1 = X\beta + Y^*\eta^* + \sum_{j=-p}^p \Delta Y_{-j}^* \gamma_j + \nu$$

- DOLS specification simply adds p leads and p lags of the first difference of Y^* to the standard cointegrating regression.
- The addition of leads and lags removes the deleterious effects that short-run dynamics of the equilibrium process ν_t have on the estimate of the cointegrating vector η^* .

Properties of DOLS Estimator of η^*

- The DOLS estimator $\hat{\eta}^*$ is consistent, asymptotically normally distributed, and efficient.
- Asymptotically valid standard errors for the individual elements of $\hat{\eta}^*$ are given by their corresponding HAC (e.g., Newey-West) standard errors.
- If T is not large relative to $p(m - 1)$, there may be so many additional regressors that finite-sample properties of the DOLS estimator $\hat{\eta}^*$ will actually be quite poor.

Testing for Cointegration

Basic idea (Engle & Granger 1987):

- If $(y_{1,t}, y_{2,t}, \dots, y_{m,t})$ are cointegrated, the true equilibrium error process ν_t must be $I(0)$.
- If they are not cointegrated, then ν_t must be $I(1)$.
- Test the null hypothesis of **no cointegration** against the alternative of cointegration by performing a unit root test on the equilibrium error process ν_t .

Residual-Based Cointegration Tests

Engle-Granger (EG) 2-step procedure:

- Choose the normalization (i.e., $\eta_1 = 1$).
- Form the cointegrating residual $\nu_t = Y_t' \eta^*$.
- Test whether or not ν_t has a unit root—that is, is an $I(1)$ process.
- Rejection of the null hypothesis at a pre-specified significance level implies that the m series are cointegrated.

Two cases to consider:

- The proposed cointegrating vector η is **pre-specified**.
- The proposed cointegrating vector η is **estimated** from the data and an estimate of the cointegrating residual is formed:

$$\hat{\nu}_t = Y_t' \hat{\eta}$$

Tests using the pre-specified cointegrating vector are much more powerful!

Testing for Cointegration when η^* is Unknown

ADF test:

$$\Delta \hat{v}_t = (\alpha - 1)\hat{v}_t + \sum_{j=1}^p \theta_j \Delta \hat{v}_{t-j} + e_t$$

- $\hat{v}_t = y_{1t} - X' \hat{\beta} - Y_{2t}' \hat{v}$
- $\hat{\eta} = \text{OLS or DOLS estimate of the cointegrating vector } \eta$

Testing for Cointegration when η^* is Unknown

Key results:

- Phillips and Ouliaris (1990) show that residual-based unit root tests applied to the estimated cointegrating residuals do **not** have the usual Dickey-Fuller distributions under the null hypothesis of no-cointegration.
- Because of the spurious regression phenomenon under the null hypothesis, the distribution of these tests have asymptotic distributions that depend on:
 - Deterministic terms in the regression used to estimate η .
 - $(m - 1)$ = number of variables Y_{2t} .
- These distributions are known as **Phillips-Ouliaris distributions** and critical values have been tabulated.

Error-Correction Model

Consider:

- $Y_t = [y_{1t} \ y_{2t}]'$ = bivariate $I(1)$ process
- Y_t is cointegrated with $\eta = [1 \ -\eta_2]'$

Error-Correction Model (ECM) (Engle & Granger (1987)):

$$\begin{aligned}\Delta y_{1t} &= \alpha_1 + \lambda_1 [y_{1t-1} - \eta y_{2t-1}] \\ &\quad + \sum_j \beta_{1j} \Delta y_{1t-j} + \sum_j \gamma_{1j} \Delta y_{2t-j} + e_{1t}\end{aligned}$$

$$\begin{aligned}\Delta y_{2t} &= \alpha_2 + \lambda_2 [y_{1t-1} - \eta y_{2t-1}] \\ &\quad + \sum_j \beta_{2j} \Delta y_{1t-j} + \sum_j \gamma_{2j} \Delta y_{2t-j} + e_{2t}\end{aligned}$$

Error Correction Model

- ECM links the long-run equilibrium relationship between y_{1t} and y_{2t} implied by cointegration with the short-run dynamic adjustment mechanism that describes how the two series react when they move out of long-run equilibrium.
- Parameters λ_1 and λ_2 measure the speed of adjustment of y_{1t} and y_{2t} to the long-run equilibrium, respectively.